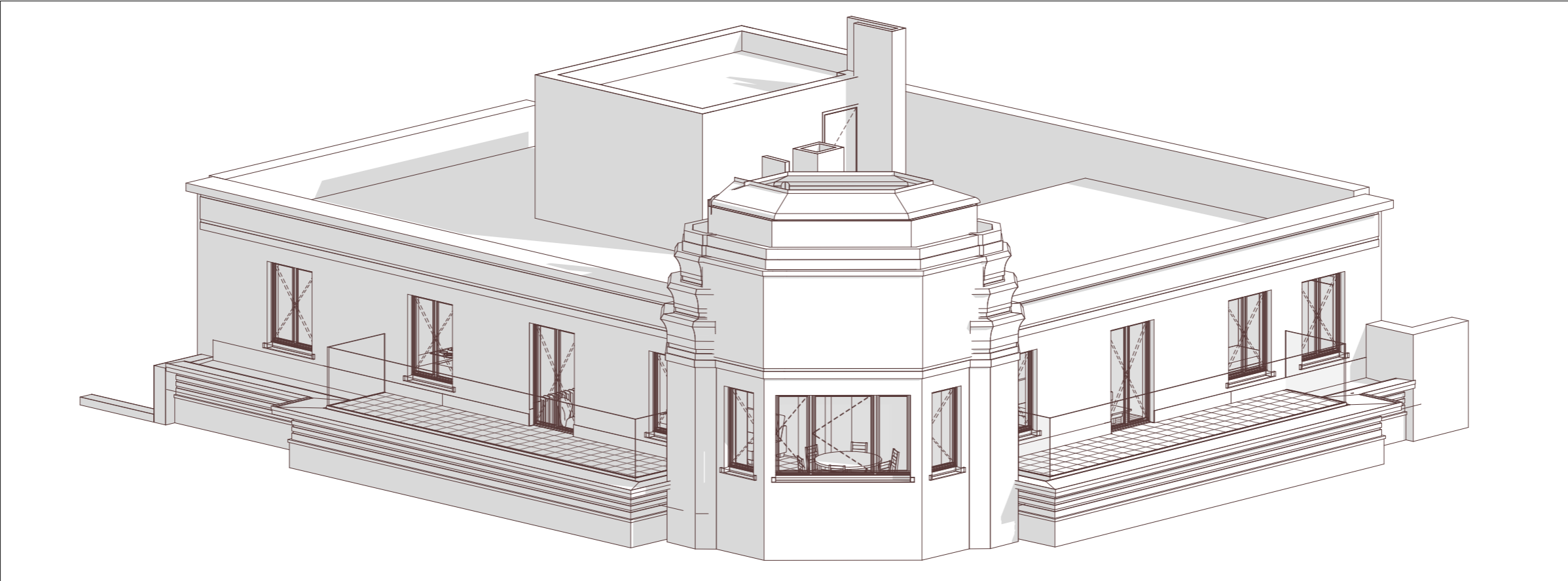


Axonometry situation existante



Axonometry situation projetée